

# Dependences



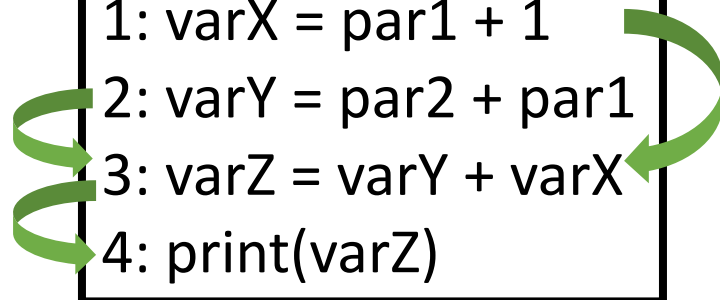
Simone Campanoni  
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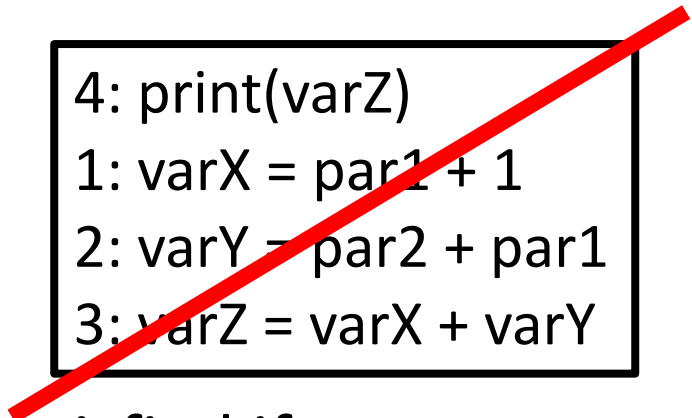
# Dependences: the big picture

- Code transformations are designed to preserve the semantics of the code given as input
  - As defined earlier, semantics of a program is the Input=>Output mapping


```
1: varX = par1 + 1
2: varY = par2 + par1
3: varZ = varY + varX
4: print(varZ)
```



```
4: print(varZ)
1: varX = par1 + 1
2: varY = par2 + par1
3: varZ = varX + varY
```

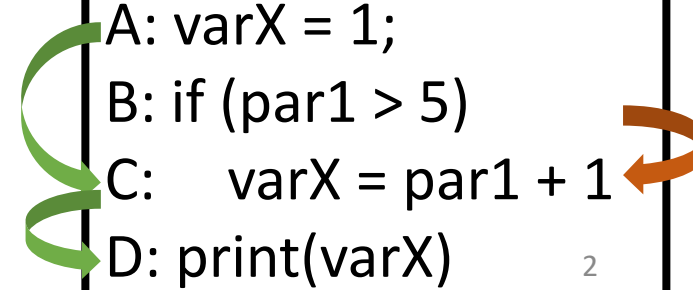


```
2: varY = par2 + par1
1: varX = par1 + 1
3: varZ = varX + varY
4: print(varZ)
```



- A dependence A -> B is satisfied if A will always execute before B
- If we satisfy **all dependences** in the code, then we will preserve I => O

```
A: varX = 1;
B: if (par1 > 5)
C:   varX = par1 + 1
D: print(varX)
```



# Outline

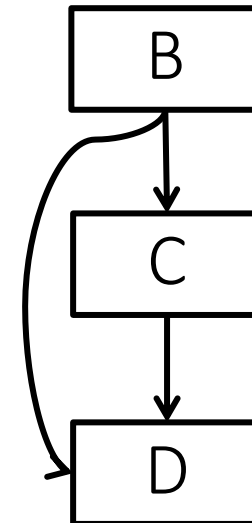
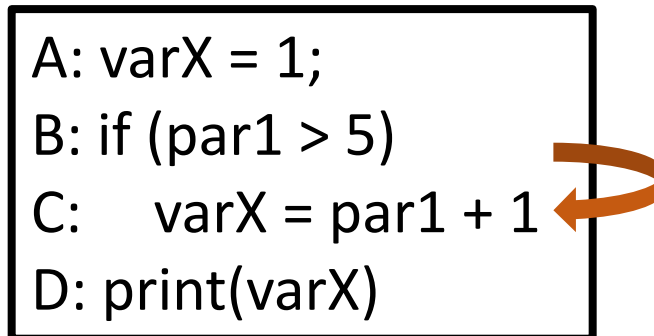
- Control dependences
- Data dependences
- Introduction to memory alias analysis

# Control dependence intuition

- Dependence: C will be executed depending on B

- How to identify C?  
(automatically)
  - Do we need a DFA?
  - We need a **Control Flow Analysis**

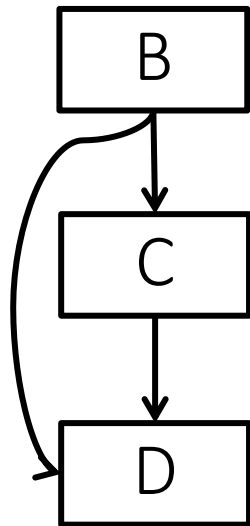
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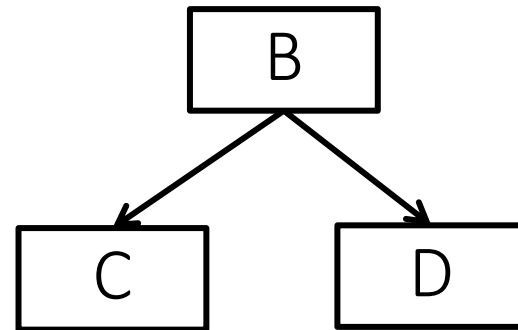
CFG

# Dominators

**Definition:** Node  $d$  dominates node  $n$  in a graph if every path from the start node to  $n$  goes through  $d$



CFG



Immediate dominator tree

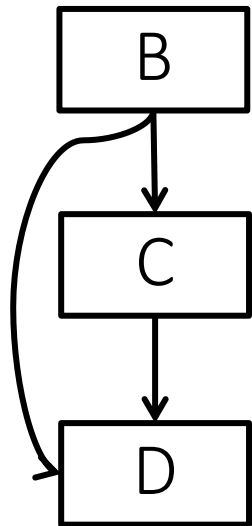
```
B: if (par1 > 5)
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D: print(varX)
```

**Are dominators useful to identify the control dependence between C and B?**

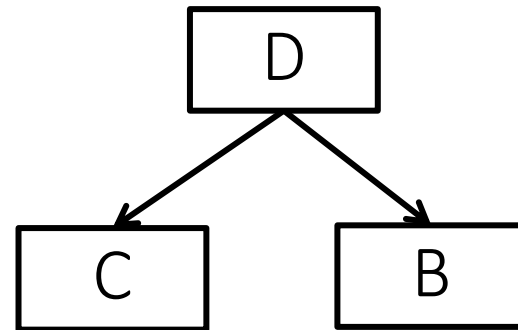
# Post-Dominators

**Assumption:** Single exit node in CFG

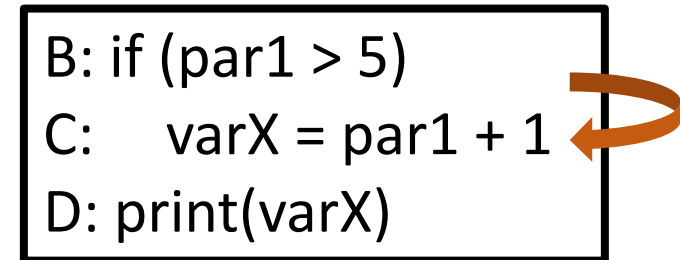
**Definition:** Node  $d$  post-dominates node  $n$  in a graph if every path from  $n$  to the exit node goes through  $d$



CFG



Immediate  
post-dominator tree



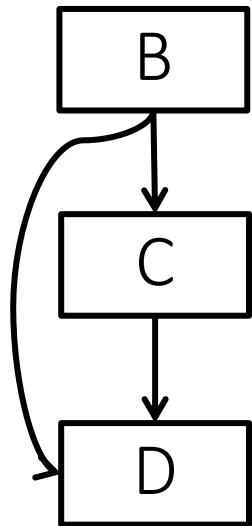
**How can we identify C and B with the post-dominator tree and the CFG?**  
***B determines whether C executes or not***

# Control dependence in our example

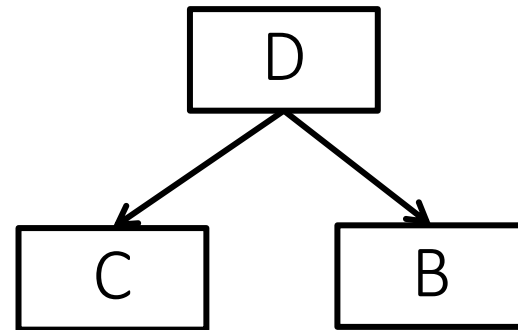
Node *C* is control-dependent on *B* because

1. *C* is the successor of *B*
2. *C* does not post-dominate *B*

*Do you see any problem?*



CFG



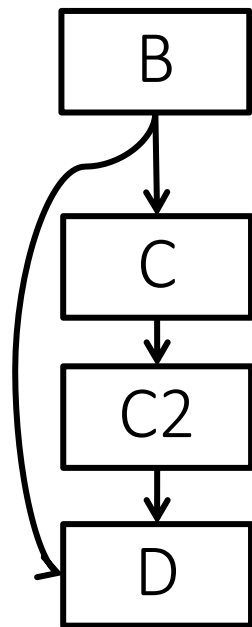
Immediate  
post-dominator tree

```
B: if (par1 > 5)
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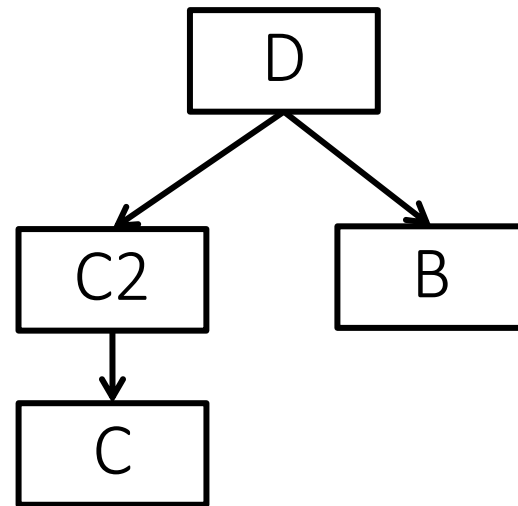
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CFG



Immediate  
post-dominator tree

```
B: if (par1 > 5)
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C2: ...
D: print(varX)
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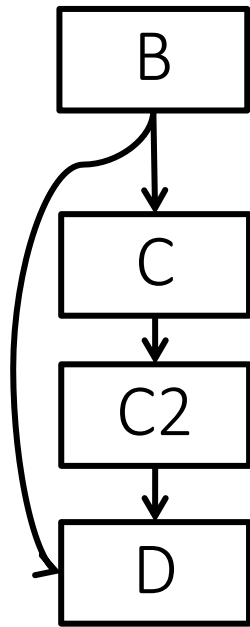
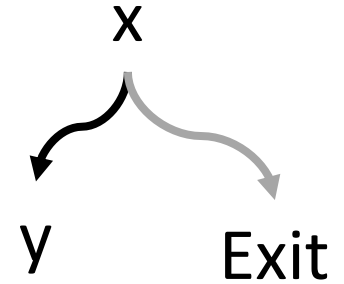


Why?

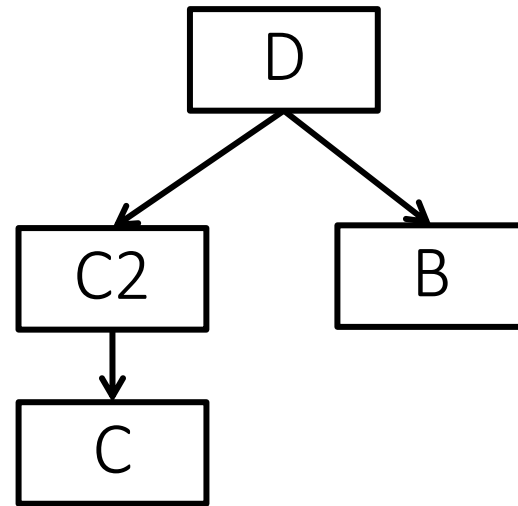
# Control dependences (almost correct)

A node  $Y$  control-dependes on another node  $X$  if and only if

1. There is a path from  $X$  to  $Y$  such that every node in that path other than  $X$  is post-dominated by  $Y$
2.  $X$  is not post-dominated by  $Y$



CFG



Immediate post-dominator tree

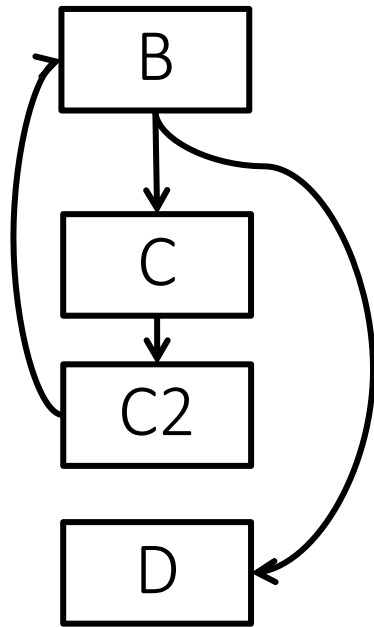
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Why?

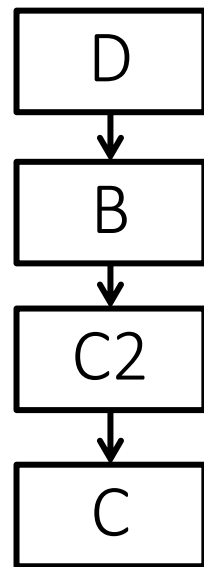
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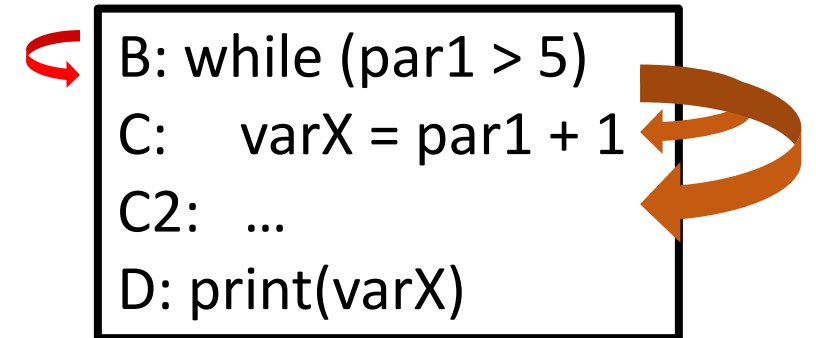
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CFG



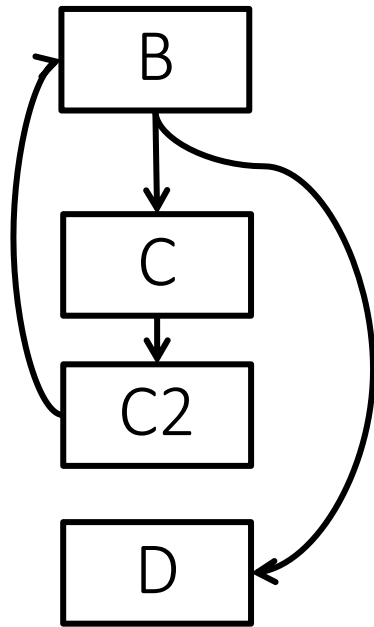
Immediate  
post-dominator tree



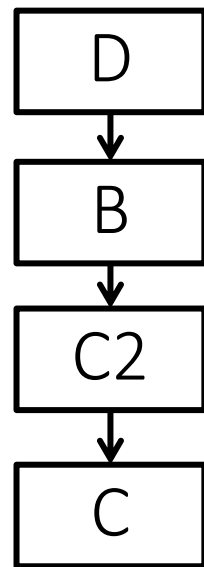
# Control dependences

A node  $Y$  control-depends on another node  $X$  if and only if

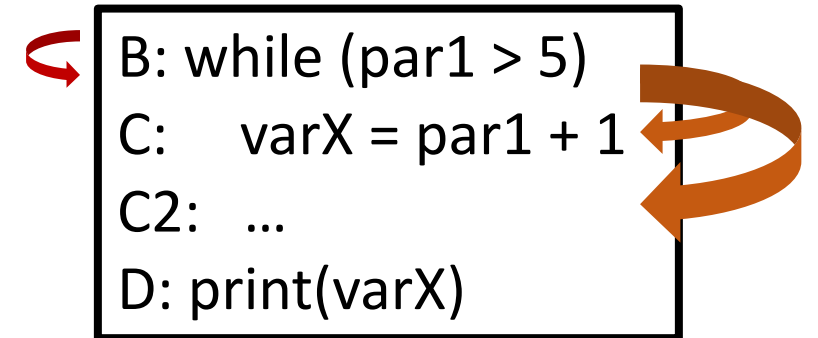
1. There is a path from  $X$  to  $Y$  such that every node in that path other than  $X$  is post-dominated by  $Y$
2.  $X$  is not **strictly** post-dominated by  $Y$



CFG

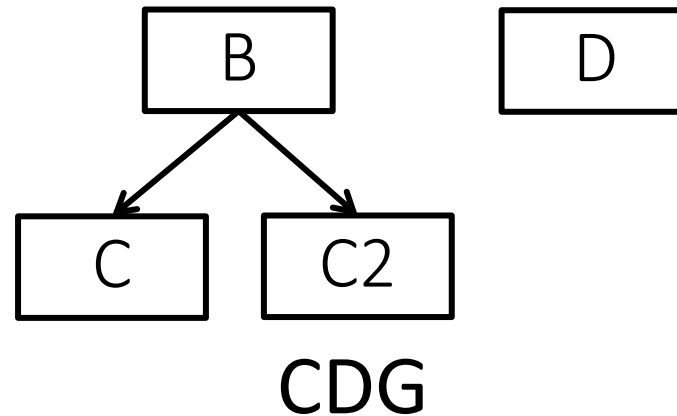
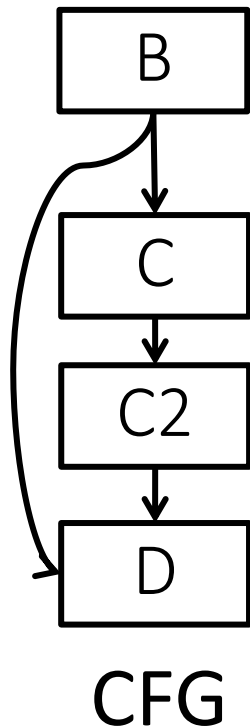


Immediate  
post-dominator tree



# Control dependence graph (CDG)

- Graph (N, E) where
  - N are basic blocks
  - Exist an edge (x,y) in E if and only if y control-depends on x



An use of CDG:

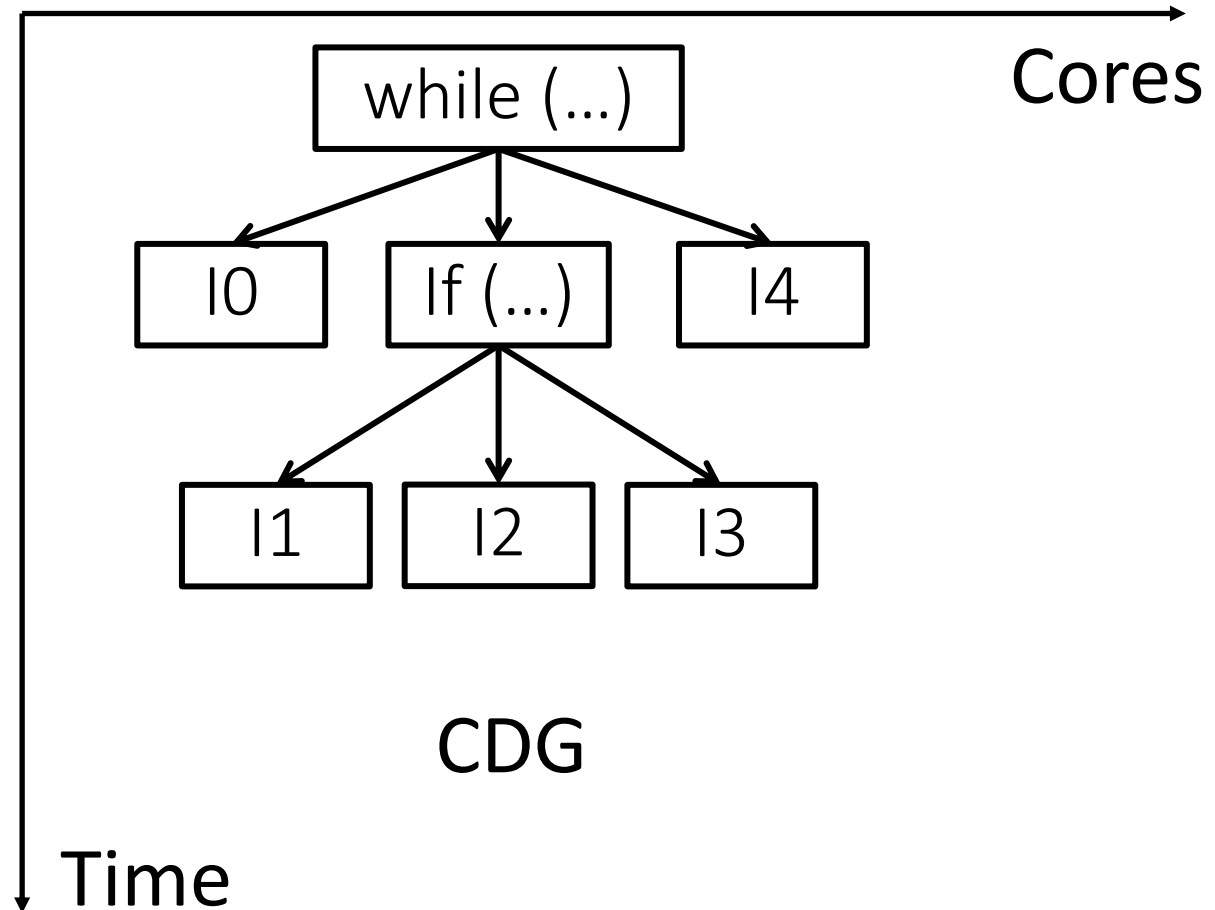
**Sequential program:** fixed order of execution

**Goal:** remove unnecessary order

Useful for parallelism

# Extracting parallelism automatically

```
while (...)  
10: ...  
   if (...){  
11:   ...  
12:   ...  
13:   ...  
   }  
14: ...  
}
```



- Assuming
  - no data dependence
  - Infinite cores
- We want to minimize the wall time of our program

# Control dependence graph

- The previous definition of control dependences

A node  $X$  is control-dependent on another node  $Y$  if and only if

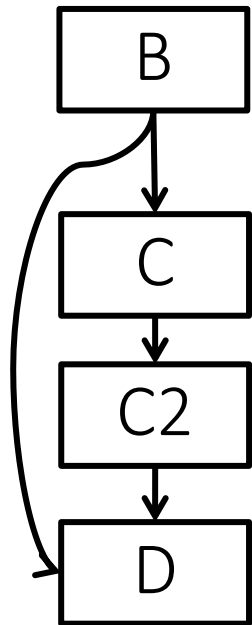
1. There is a path from  $X$  to  $Y$  such that every node in that path other than  $X$  is post-dominated by  $Y$
2.  $X$  is not strictly post-dominated by  $Y$

- Naïve implementation:  
Iterate over all pair of instructions  
Check conditions 1 and 2 for each pair  
 $O(N^2)$
- Can we do better?

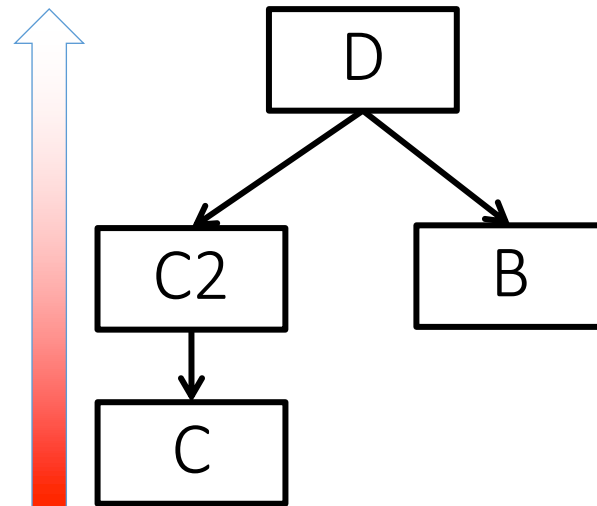
# Control dependence graph: algorithm

A node  $Y$  control-dependes on another node  $X$  if and only if

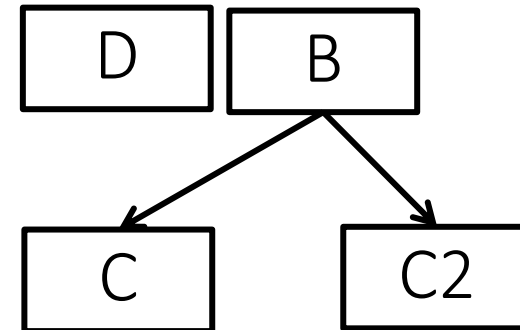
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CFG



Immediate  
post-dominator tree



CDG

(B,C)  
(B,C2)

How can we compute  
the CDG?

# Outline

- Control dependences
- Data dependences
- Introduction to memory alias analysis



# Data dependence

Three types of data dependence (assuming int a,b,c):

- Flow (True) dependence : read-after-write

```
a = c * 10;
```


```
b = 2 * a + c;
```



- Anti Dependency: write-after-read

```
a = b * 4 + c;
```


```
c = b + 40;
```



- Output Dependence: write-after-write

```
a = b * c ;
```

```
a = b + c + 10;
```



# Data dependences

- Gives constraints on parallelism that must be satisfied
- Must be satisfied to have correct program
  - How can we satisfy data dependences?
- Any order that does not violate these dependences is correct!

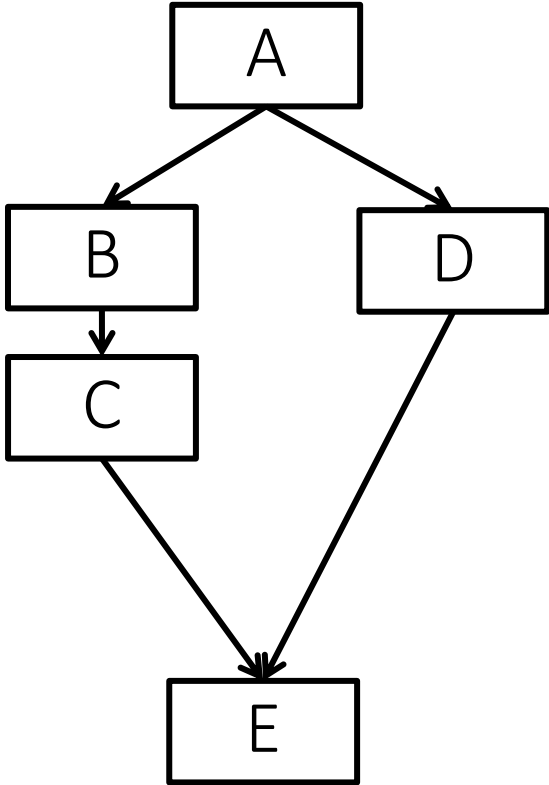
# Data dependence graph (DDG)

- Graph  $(N, E)$  where
  - $N$  are instructions
  - Exist an edge  $(x,y)$  in  $E$  if and only if  $y$  is data dependent on  $x$

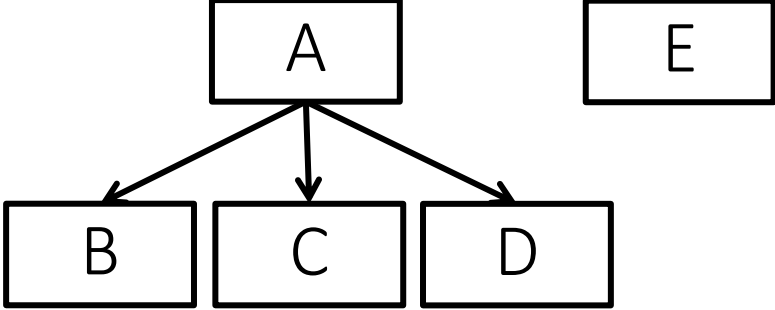
## Differences between CDG and DDG

- Granularity
- Structure vs. content

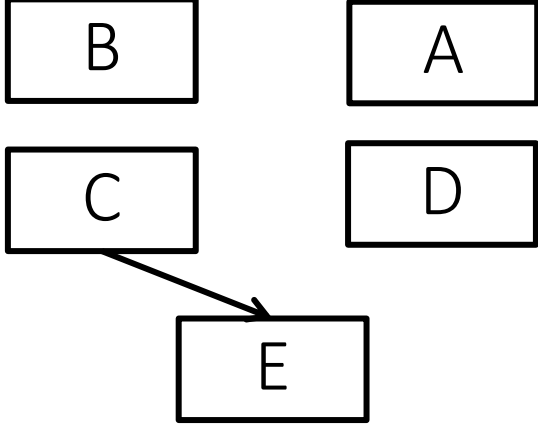
# Dependence example



CFG



CDG



DDG

What are the possible executions that preserve the original semantics of the program?

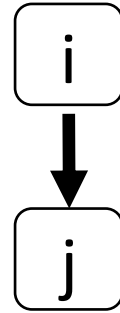
- A B C E
- A D E
- A C B E
- A E D
- A C E B

# Dependence descriptors

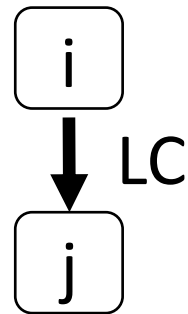
- Data vs. control
- RAW, WAR, WAW
- ...

# Loop-carried data dependences

```
while(...){  
  i: x = ...;  
  j: *p = x + 1;  
  ...  
}
```

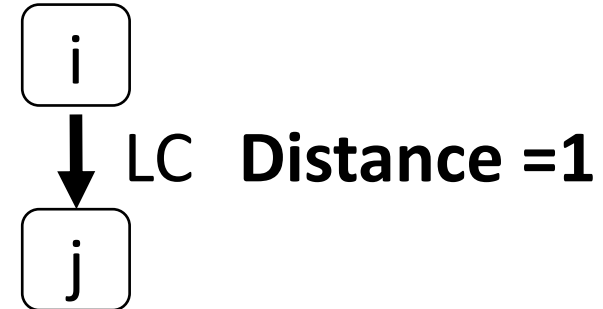


```
while(...){  
  j: *p = x + 1;  
  i: x = ...;  
  ...  
}
```

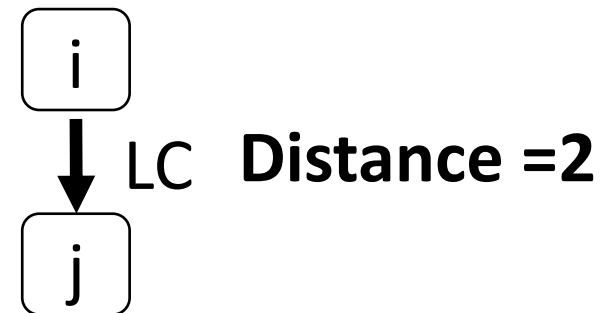


# Loop-carried data dependences

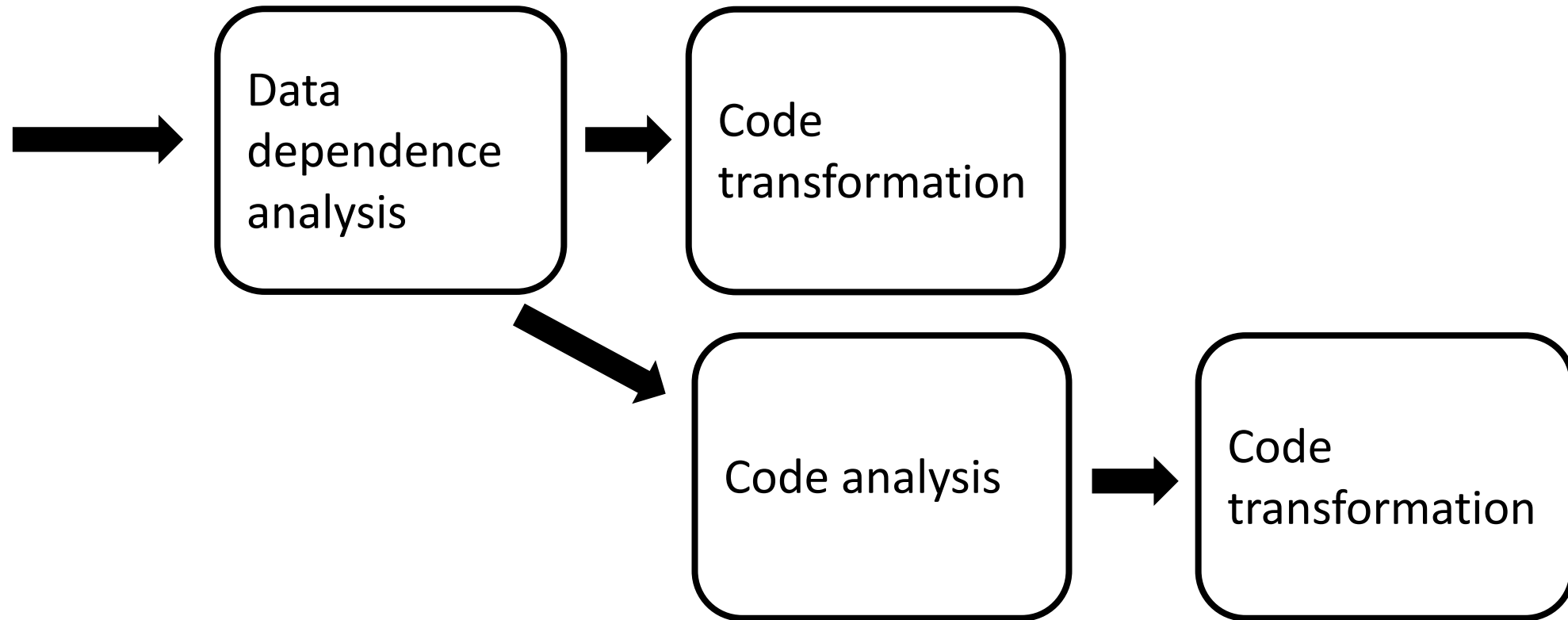
```
while(...){  
  j: *p = x + 1;  
  i: x = ...;  
  ...  
}
```



```
while(...){  
  j: *p = A[i-2] + 1;  
  i: A[i] = ...;  
  k: i++;  
}
```



# Data dependence analysis and others





# (Variable) Data dependences in LLVM

Any idea?

# (Memory) Data dependences in LLVM

- Memory data dependences are computed by MemoryDependenceAnalysis

```
#include "llvm/Analysis/MemoryDependenceAnalysis.h"
```

```
void getAnalysisUsage(AnalysisUsage &AU) const override {  
    AU.addRequired< MemoryDependenceWrapperPass >();  
    return;  
}
```

- To get the output of the data dependence analysis:

```
MemoryDependenceResults &MD = getAnalysis< MemoryDependenceWrapperPass >().getMemDep();
```

- To get a dependency

```
MemDepResult memInstDeps = MD.getDependency(memInst);  
auto memInst2 = memInstDeps.getInst();
```

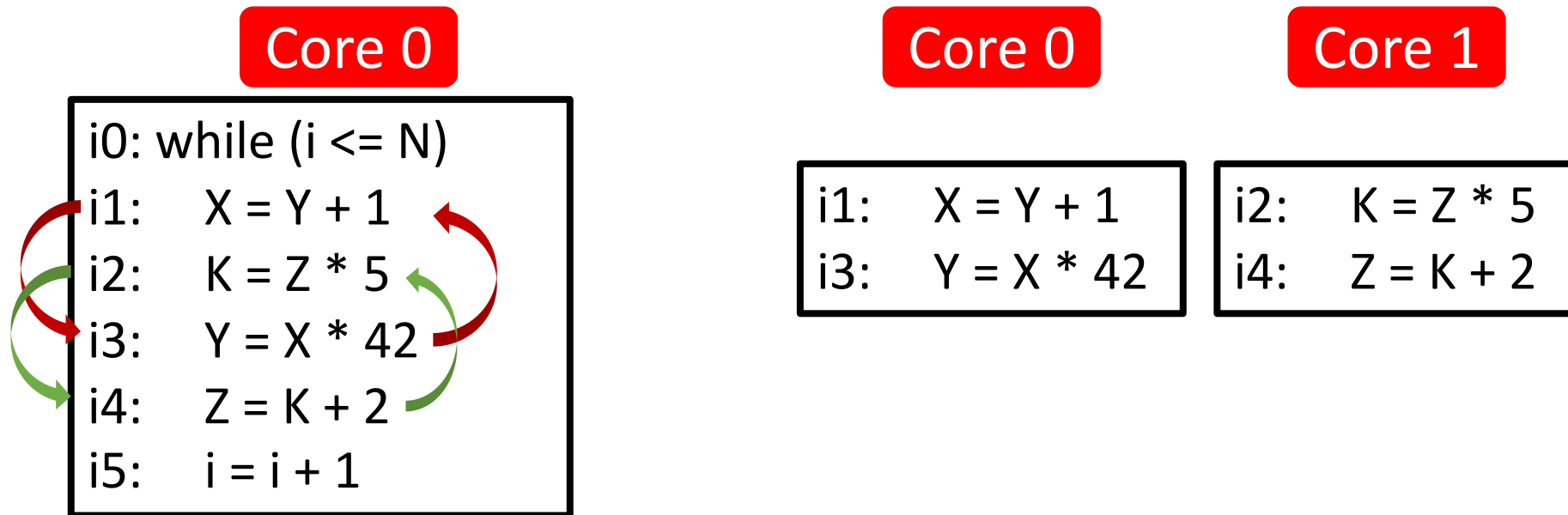
# Program dependence graph

- Program Dependence Graph = Control Dependence Graph + Data Dependences
- Facilitates performing most traditional optimizations
  - Constant folding, scalar propagation, common subexpression elimination, code motion, strength reduction
- Requires only single walk over PDG

# Strongly Connected Component (SCC)

Often you need to partition instructions in groups

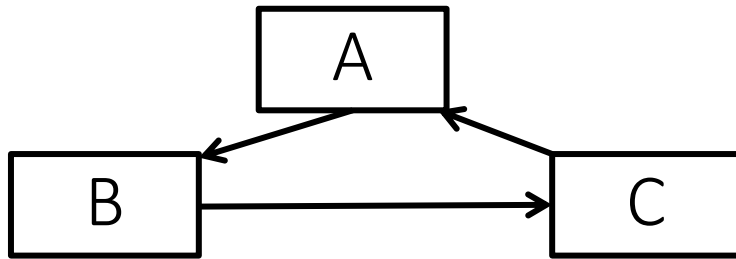
- Where each group is composed of instructions that depend on each other



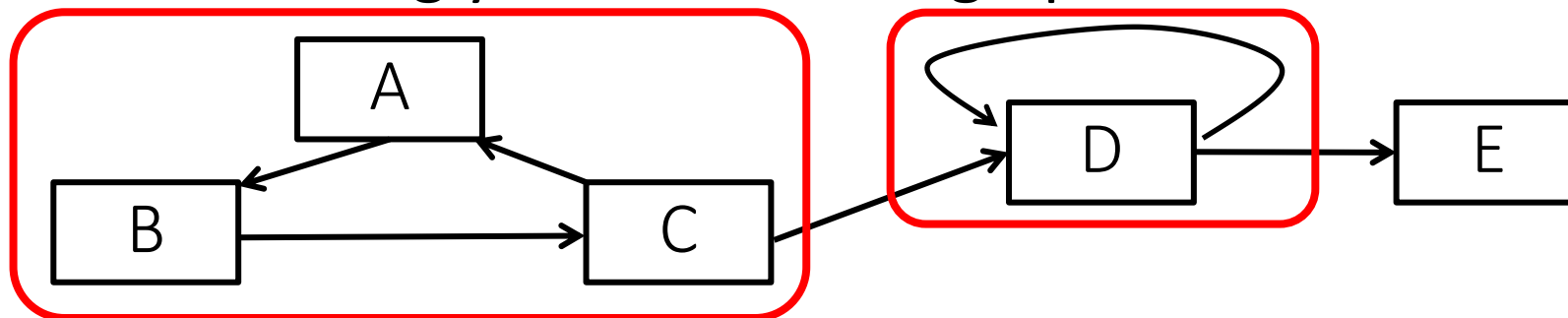
Different colors  $\leftrightarrow$  different cycles in the PDG  $\Rightarrow$  different cores

# Strongly Connected Component (SCC)

- A directed graph is strongly connected if there is a path between all pairs of vertices

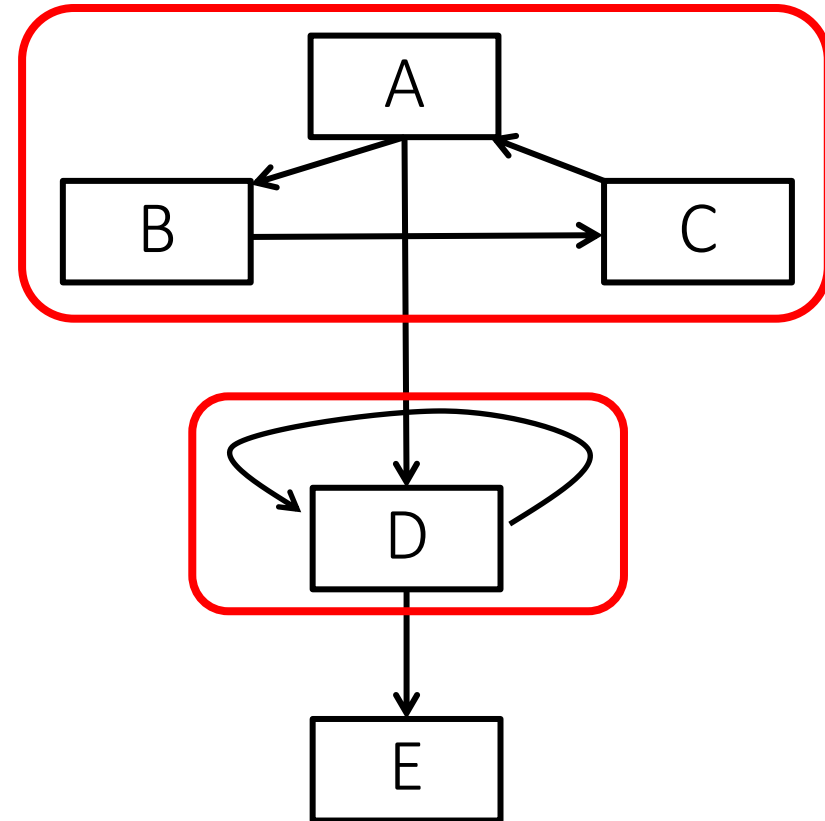


- A strongly connected component (**SCC**) of a directed graph is a maximal strongly connected subgraph



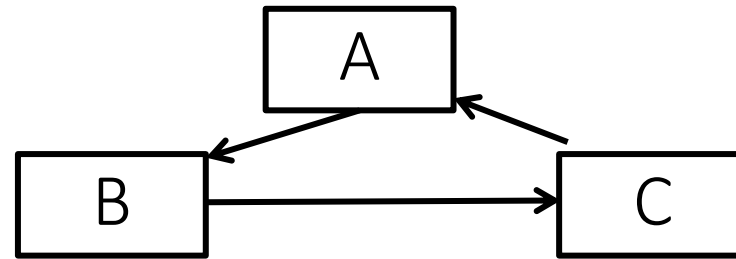
# SCCDAG

- From the PDG
- To the SCC identifications

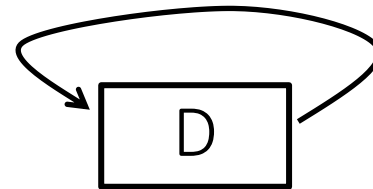


# SCCDAG

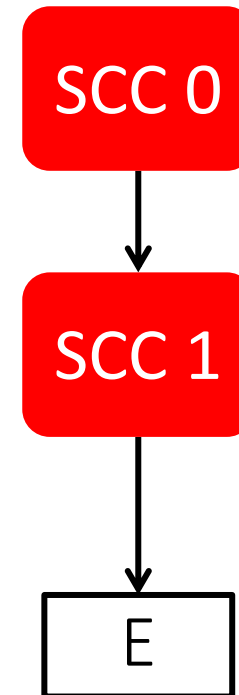
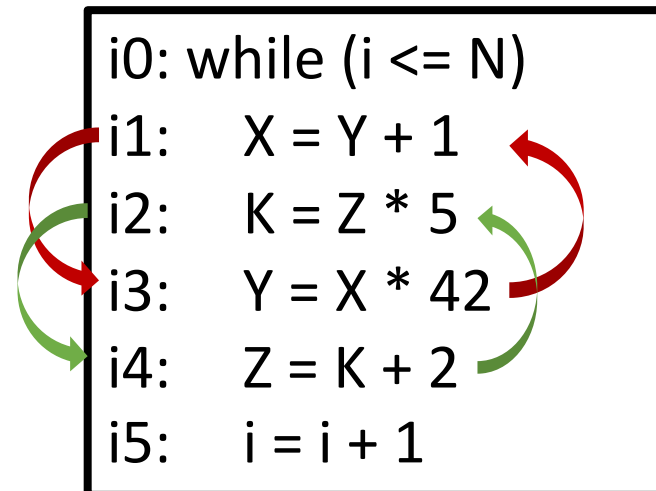
- From the PDG




- To the SCC identifications



- To the SCCDAG



# Identify SCCs

- Tarjan's algorithm  In practice, this is faster
  - It utilizes the property that nodes of a strongly connected component form a subtree in the DFS spanning tree of the graph
  - Complexity:  $O(|N| + |E|)$
- Kosaraju's algorithm
  - It utilizes the property that the transpose graph (the same graph with the direction of every edge reversed) has the same strongly connected components as the original graph
  - Performs two DFSs on the graph
  - It is similar to the method for finding the topological sorting
  - Complexity:  $O(|N| + |E|)$



# Identify SCCs in LLVM (Tarjan's algorithm)

- Two template APIs to iterate over SCCs of a graph G:

`scc_begin()` and `scc_end()`

```
for (auto sccl = scc_begin(pdg); sccl != scc_end(pdg); ++sccl) {  
    auto const &sccl = *sccl;  
}
```

- These APIs assume the method `getEntryNode()` can be called from the object given as input

- The return type of `getEntryNode()` set the type of `sccl`

E.g., if we have the following method for our `pdg:MyNodeT * getEntryNode ()`

Then `sccl` is of type `std::vector<MyNodeT *>` and therefore

```
const std::vector<MyNodeT *> &sccl = *sccl;
```

# Outline

- Control dependences
- Data dependences
- **Introduction to memory alias analysis**

# Memory alias analysis: the problem

- We want to
  - Execute  $j$  in parallel with  $i$  (extracting parallelism)
  - Move  $j$  before  $i$  (code scheduling)
- Does  $j$  depend on  $i$ ?

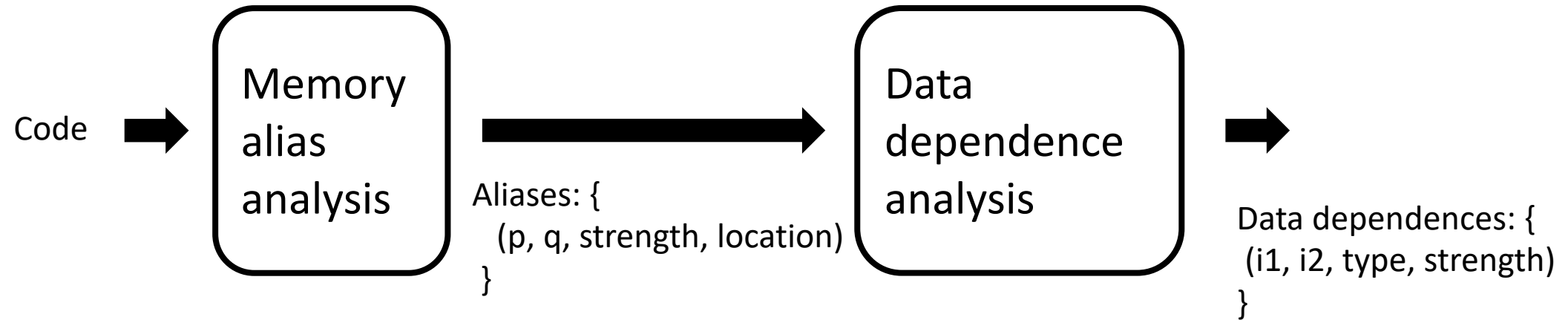
```
i: (*p) = varA + 1  
j: varB = (*q) * 2
```

```
i: obj1.f = varA + 1  
j: varB = obj2.f * 2
```

- Do  $p$  and  $q$  point to the same memory location?
  - Does  $q$  alias  $p$ ?



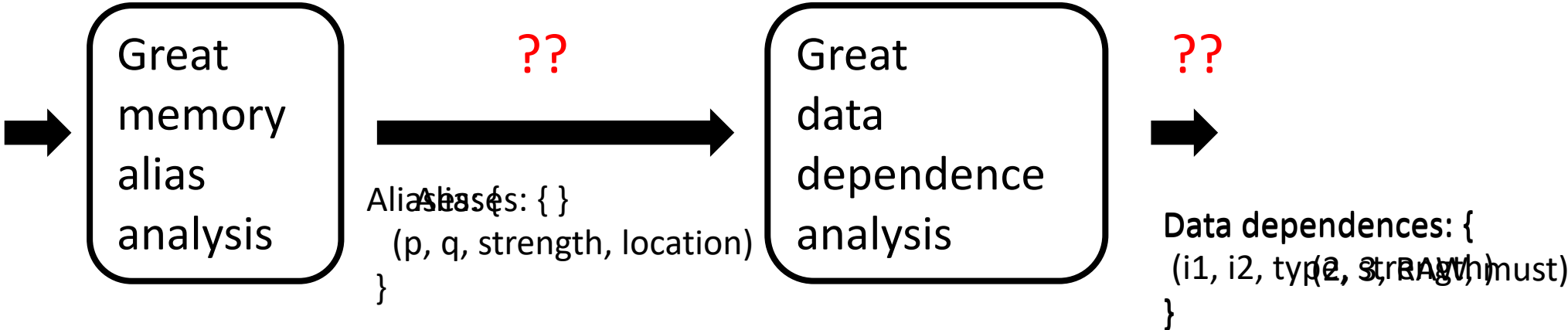
# Memory alias/data dependence analysis



# Memory alias/data dependence analysis

Can we optimize the code knowing these dependences?

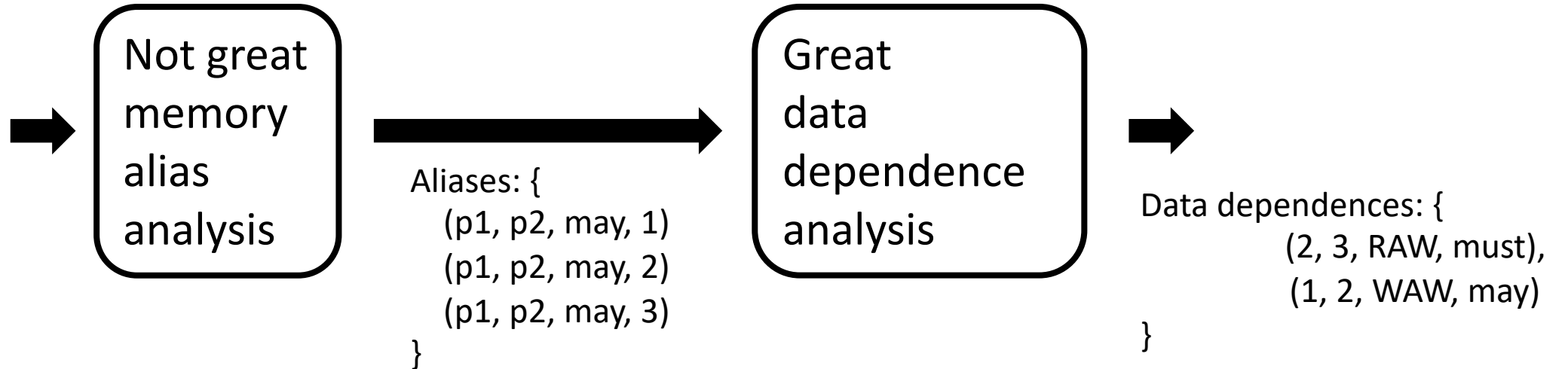
```
1: *p1 = ...  
2: *p2 = ...  
3: v1 = *p2
```



Oracle:  
p2 and p1 points to different memory locations always

# Memory alias/data dependence analysis

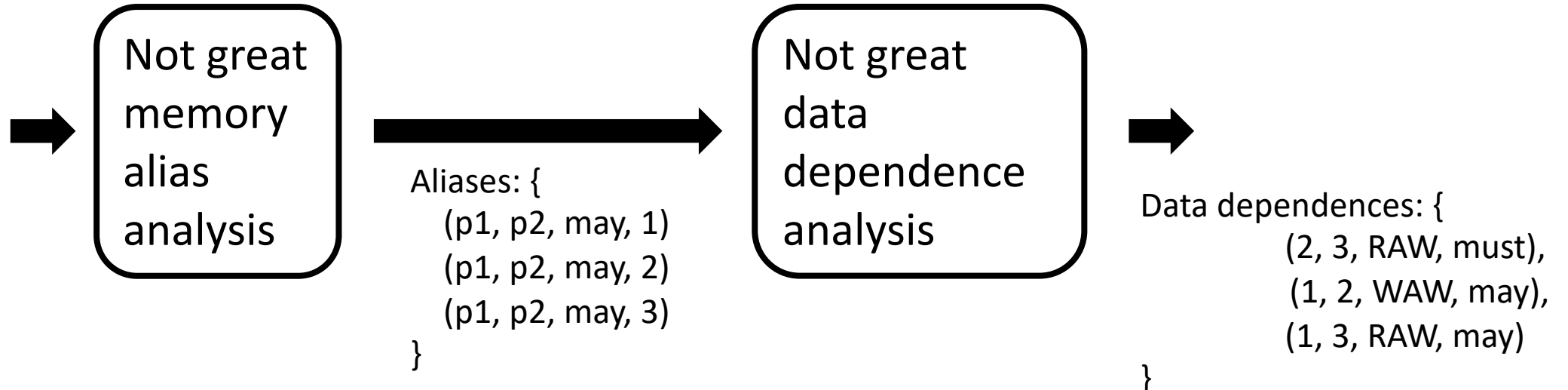
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# Memory alias/data dependence analysis

1: \*p1 = ...  
2: \*p2 = ...  
3: v1 = \*p2



Oracle:

p2 and p1 points to different memory locations always

Analysis output:

Everything depends on everything else

# Memory alias/data dependence analysis

**Inaccuracies on either memory alias analysis  
or data dependence analysis**

**leads to “apparent” dependences**

- **More constraints on code transformations**
- **Reduce the aggressiveness of code transformations**
- **Reduce performance obtained**

Oracle:

p2 and p1 points to different memory locations always

Analysis output:

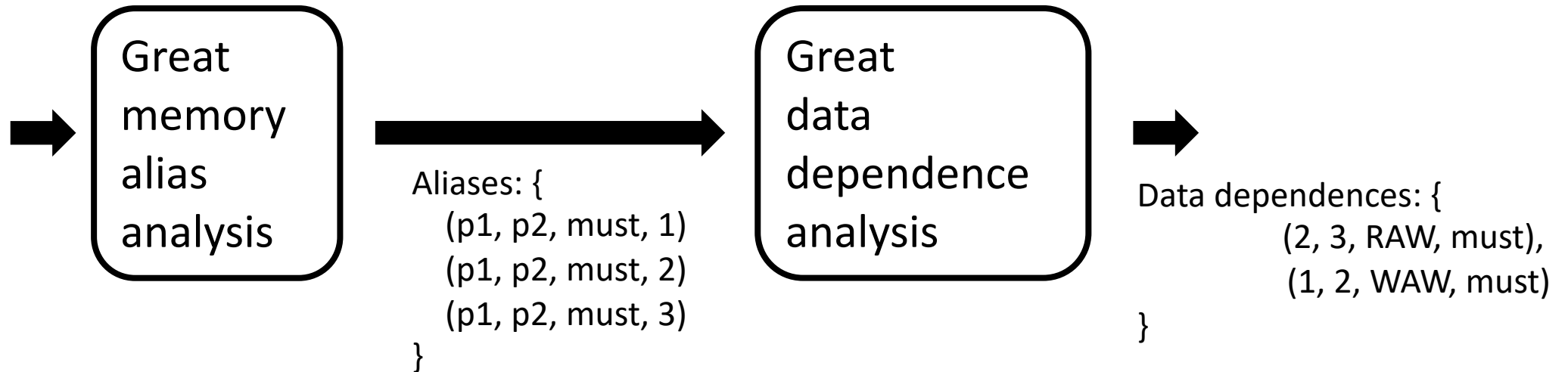
Everything depends on everything else



# Memory alias/data dependence analysis

Can we optimize the code knowing these dependences?

~~1: \*p1 = ...~~  
2: \*p2 = ...  
3: v1 = \*p2



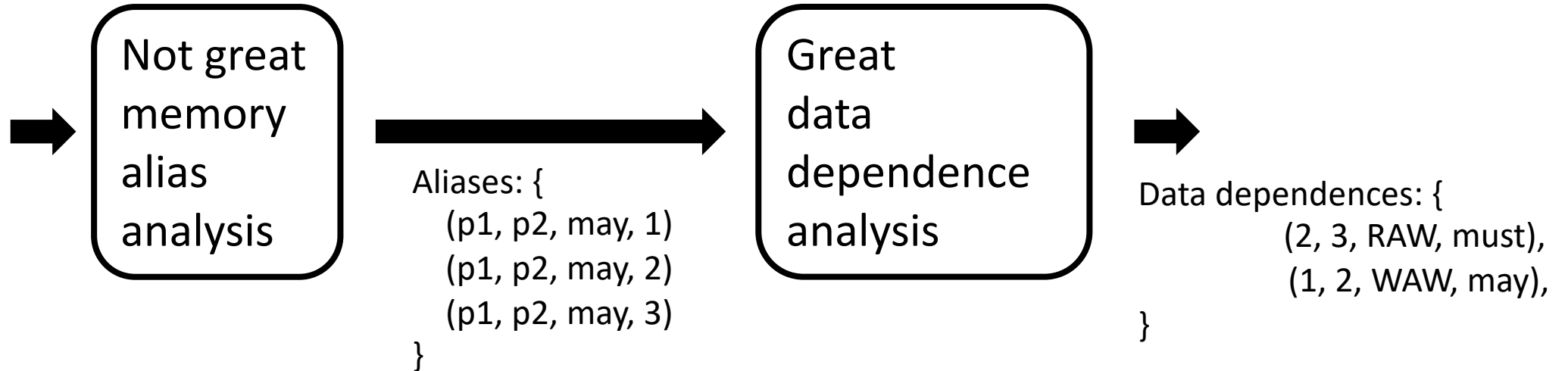
Oracle:

p2 and p1 points to the same memory location always

# Memory alias/data dependence analysis

**We cannot delete instruction 1**

1: \*p1 = ...  
2: \*p2 = ...  
3: v1 = \*p2



Oracle:  
p2 and p1 points to the same memory location always

# Memory alias/data dependence analysis

## Useless output

- **Alias analysis:**  
a pointer may alias to another one
- **Data dependence analysis:**  
an instruction may depend on another one

**... may ...**



# Memory alias/data dependence analysis and code analysis/transformation

## **Code analysis and transformation**

**that rely on memory alias analysis  
and/or data dependence analysis**

**must be correct**

**independently with the accuracy of  
memory alias analysis  
and/or data dependence analysis**

Always have faith in your ability

Success will come your way eventually

**Best of luck!**